Review of the Atmospheric Channel in FSO Communication System

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ABSTRACT: This paper reviews the atmospheric channel and begins by providing a general description of the atmospheric channel with particular emphasis on the various impairments that adversely affect the transmitted optical signal. The attenuation due to beam spreading, absorption, scattering, pointing and coupling loss are discussed in this paper. An overview of atmospheric turbulence (and how it leads to scintillation) is provided and various probabilistic scintillation models used in describing the turbulent channel are reviewed. The use of Monte Carlo (MC) simulation methods for atmospheric turbulence modelling is discussed. Some of the turbulence mitigation methods already proposed in literature such as aperture averaging, maximum likelihood sequence detector (MLSD) and spatial diversity were also reviewed in this paper.

KEYWORDS: Atmospheric turbulence, beam spreading, absorption, scattering, Monte Carlo simulation

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I. INTRODUCTION

The optical signal propagated through the atmospheric channel is usually attenuated due to its susceptibility to various impairments [1]. Line-of-sight (LOS) impairments such as physical obstructions along the propagation path can be reduced (or eliminated) by correctly positioning the transmitter and receiver. However, impairments dependent on the geographic location and time such as fog, rain, snow, haze and atmospheric suspended particles (mainly concentrated near the earth surface) such as aerosols and gases presents a greater challenge [2-4]. These impairments result in scattering (i.e. directional change in the transmitted signal due to suspended particles) and absorption (i.e. conversion of photon to heat after colliding with atmospheric molecules such as nitrogen, oxygen, argon and carbon dioxide). Absorption is mainly wavelength dependent and its effect can be mitigated by choosing an appropriate wavelength for the transmitted signal. Also, scattering (which makes the most contribution to the atmospheric attenuation factor) can be classified (based on the suspended particles radius and wavelength) into three different types namely Rayleigh, Mie and non-selective (described with geometric optics) scattering [2, 3, 5].

A major impairment to seamless signal transmission through the atmosphere is thermal inhomogeneity. These thermal inhomogenities cause random temporal and spatial refractive index changes which results in large-scale and small-scale eddies (i.e. atmospheric turbulence) that haphazardly interacts with the transmitted optical signal [1, 6]. Atmospheric turbulence causes scintillation (i.e. optical signal power fluctuation) and it significantly affects system performance [1, 7]. The effect of atmospheric turbulence becomes even more severe in long distance communication [5, 8]. It is essential that system designers understand the various impairments in the atmospheric channel so that adequate penalties can be incorporated where required.

II. ATMOSPHERIC TURBULENCE

The earth surface consists of various packets of air varying in size and temperature [1]. This inhomogeneity in the thermal state of the atmosphere causes refractive index changes (mainly due to temperature fluctuations [6]) referred to as optical turbulence [9-11]. An approximation of the refractive index can be given as [6].

$$n = 1 + 77.6 \times 10^{-6} \left(1 + 7.52 \times 10^{-3} \lambda (nm)^{-2} \right) \frac{p_{atm}(mbar)}{T(K)}$$
(1)

where p_{atm} and T represents the atmospheric pressure and temperature respectively. The packets of air in the atmosphere are then further split by optical turbulence into turbulence eddies; which can be classified into inner scales l_0 and outer scales L_0 depending on their sizes (shown in Fig. 1) [3, 6, 12]. Typically sizes of l_0 and L_0 are 1 to 10 mm (near the earth surface) and 1 to 100 m respectively [6]. According to Kolmogorov, the power spectral density of the refractive index random fluctuations in the inertia subrange (eddies with sizes

(2)

between the outer and inner scale [3]) is given as [3, 6]

$$\phi_n(\kappa) = 0.033 C_n^2 \kappa^{-11/3}; \qquad 1/L_0 << \kappa << 1/l_0$$

where C_n^2 represents the refractive index structure parameter and $k = 2\pi/\lambda$ represents the optical wave number where λ represents the optical wavelength. Since the Kolmogorov spectrum model is only limited to the inertia subrange, other models have been derived to cover the outer and inner scales. For instance, the spectrum model originally developed by Novikov [6] for velocity fluctuations but later adapted by Tatarskii [6] for refractive index random fluctuations in both the inertia and dissipation ranges (eddies with sizes smaller than the inner scale) is given as [3, 6]

$$\phi_n(\kappa) = 0.033 C_n^2 \kappa^{-11/3} \exp\left(-\frac{\kappa^2}{\kappa_m^2}\right); \qquad \kappa >> 1/l_0; \quad \kappa_m = 5.92/l_0 \tag{3}$$

While another spectrum model (that incorporates the outer scale) was developed by Andrew as shown in [6], it is noteworthy that free-space optical (FSO) links are mainly affected by the energy of eddies in the inertia subrange [6]. The atmospheric turbulence strength (i.e. scintillation magnitude) can be described by a scintillation index given as [12]

$$\sigma_l^2 = \frac{\left\langle I^2 \right\rangle - \left\langle I \right\rangle^2}{\left\langle I \right\rangle^2} \tag{4}$$

where I and $\langle I \rangle$ represents the optical signal irradiance and average irradiance respectively. The effect of atmospheric turbulence is more significant when a point receiver is used due to the varying degree of beam intensity [6].



Fig. 1: Diagrammatic representation of a fluctuating signal due to the atmospheric turbulence [1].

2.1 Probabilistic Scintillation Models

Various statistical models (representing the randomly varying signal intensity) have been used to describe atmospheric-induced turbulence fading [12]. The lognormal distribution is commonly used to characterise the weak turbulence regime [9, 13] and the K distribution (which is consistent with experimental results [14]) is used to characterise the strong turbulence regime [15, 16]. Compared to the lognormal distribution, the gamma-gamma distribution used to characterise the weak to strong turbulence regimes [17, 18] shows better agreement between experimental and theoretical data [6, 14]. In a saturated turbulence regime, the negative exponential distribution has proved to give a better fit when compared with theoretical data [19]. Note that a plane wave assumption is made for the received optical waves.

2.1.1 Lognormal Turbulence Model

When light propagates through the atmosphere, it experiences phase delay and scattering [11]. By applying the central limit theorem, the light's log-amplitude has a Gaussian marginal distribution from which the lognormal probability density function (PDF) can be obtained as [7, 9, 13]

$$f_{LN_{I}}(I,\langle I\rangle) = \frac{1}{I\sqrt{2\pi\sigma_{l}^{2}}} \exp\left\{-\frac{\left[\ln(I/\langle I\rangle) + \frac{1}{2}\sigma_{l}^{2}\right]^{2}}{2\sigma_{l}^{2}}\right\}; \qquad I > 0$$
(5)

It is computationally convenient to define a paramater h, which can be used to describe the varying channel loss or gain due to atmospheric turbulence. h has a mean value of 1, and in the turbulent free limit, this mean value is attained at all times. With $h = I/\langle I \rangle$ and by transforming random variables (i.e. $f_{LN_I}(I)dI = f_{LN_h}(h)dh$), the lognormal PDF is given with respect to h as

$$f_{LN_{h}}(h) = \frac{1}{h\sqrt{2\pi\sigma_{l}^{2}}} \exp\left\{-\frac{\left[\ln(h) + \frac{1}{2}\sigma_{l}^{2}\right]^{2}}{2\sigma_{l}^{2}}\right\}; \qquad h > 0$$
(6)

where the variance of the natural logarithm of the irradiance (i.e. the scintillation index given in (3.4)) can be obtained as [1]

$$\sigma_l^2 = \exp\left[\frac{0.49\sigma_R^2}{\left(1 + \left(1.11\sigma_R^{12/5}\right)\right)^{7/6}} + \frac{0.51\sigma_R^2}{\left(1 + \left(0.69\sigma_R^{12/5}\right)\right)^{5/6}}\right] - 1$$
(7)

where σ_R^2 , the Rytov variance used to characterise the different turbulence regimes is given as [12]

$$\sigma_R^2 = 1.23 C_n^2 k^{7/6} D^{11/6} \tag{8}$$

Note that the weak, moderate, strong and saturated turbulence regimes can be described by $\sigma_R^2 < 1$, $\sigma_R^2 \sim 1$, $\sigma_R^2 > 1$ and $\sigma_R^2 \rightarrow \infty$ respectively [7]. Even though the Rytov variance can be used to describe the different turbulence levels for the lognormal distribution, experimental results have shown that the lognormal approximation is only valid for the weak turbulence regime because at higher turbulence levels, the multiple scattering experienced is not accounted for in the Rytov approximation [1]. The lognormal PDF is shown in Fig. 2 for different Rytov variance values. In Fig. 2, it is observed that as the turbulence level increases, the PDF becomes more skewed to the left with longer tails to the right. This shows how much the channel inhomogeneity has adversely affected the irradiance fluctuation.



Fig. 2: Lognormal PDFs against h for different Rytov variance values.

2.1.2 Gamma-Gamma Turbulence Model

The fluctuations experienced by an optical signal propagating through a turbulent atmosphere consists of small-scale and large-scale effects. The small-scale effects (scattering) are caused by eddies smaller than either the Fresnel zone $\sqrt{D/k}$ or the coherence radius ρ_0 while the large-scale effects (refraction) are caused

by eddies larger than the Fresnel zone or the scattering disk $D/k p_0$ [20]. Thus, the unconditional gammagamma PDF (which is obtained from the contributions of the small-scale and large-scale effects) can be given as [14, 17, 18, 20]

$$f_{GG_{I}}\left(I,\left\langle I\right\rangle\right) = \frac{2(\alpha\beta)^{(\alpha+\beta)/2}}{\Gamma(\alpha)\Gamma(\beta)} \left(\frac{I}{\left\langle I\right\rangle}\right)^{\left(\frac{\alpha+\beta}{2}\right)-1} K_{\alpha-\beta}\left(2\sqrt{\alpha\beta\left(\frac{I}{\left\langle I\right\rangle}\right)}\right); \quad I > 0; \tag{9}$$

where α and β are the number of large and small scale eddies due to the scattering process respectively, $\Gamma(.)$ is the Gamma function and $K_u(.)$ is the modified Bessel function of the second kind with order, u. The unconditional gamma-gamma PDF is obtained with respect to h as

$$f_{GG_h}(h) = \frac{2(\alpha\beta)^{(\alpha+\beta)/2}}{\Gamma(\alpha)\Gamma(\beta)} h^{\left(\frac{\alpha+\beta}{2}\right)-1} K_{\alpha-\beta}\left(2\sqrt{\alpha\beta h}\right), \qquad h > 0;$$
(10)

where the parameters α and β are defined as [7, 20]

$$\alpha = \left\{ \exp\left[\frac{0.49\sigma_R^2}{\left(1 + \left(1.11\sigma_R^{12/5}\right)\right)^{7/6}}\right] - 1 \right\}^{-1}$$
(11)
$$\beta = \left\{ \exp\left[\frac{0.51\sigma_R^2}{\left(1 + \left(0.69\sigma_R^{12/5}\right)\right)^{5/6}}\right] - 1 \right\}^{-1}$$
(12)

The gamma-gamma PDF is shown in Fig. 3 for the weak, moderate and strong turbulence regimes. Fig. 3 shows that as the turbulence strength increases, the PDF spreads out more. As earlier stated, the gamma-gamma distribution, which shows excellent agreement between experimental and theoretical data when used to characterise the weak to strong turbulence regimes is preferred for turbulence modelling in many applications [6, 14]. Also, it can be observed in Fig. 3 that as $\beta \rightarrow 1$ (stronger turbulence), the gamma-gamma distribution tends towards a K distribution.



Fig. 3: Gamma-gamma PDFs against h for different turbulence strengths.

2.1.3 K Turbulence Model

The K distribution (arising from two independent distributions; the negative exponential and gamma distributions) is widely accepted for modelling the strong atmospheric turbulence regime because it gives a good agreement with experimental data [14, 15]. The unconditional PDF of the K distribution is given as [14-16]

$$f_{K_{I}}(I,\langle I\rangle) = \frac{2\alpha}{\Gamma(\alpha)} \left(\alpha \left(\frac{I}{\langle I\rangle}\right)\right)^{\left(\frac{\alpha-1}{2}\right)} K_{\alpha-1} \left(2\sqrt{\alpha \left(\frac{I}{\langle I\rangle}\right)}\right); \qquad I > 0;$$
(13)

which is written with respect to h as

 $f_{K_h}(h) = \frac{2\alpha}{\Gamma(\alpha)} (\alpha h)^{\left(\frac{\alpha-1}{2}\right)} K_{\alpha-1} \left(2\sqrt{\alpha h} \right), \qquad h > 0;$ (14)

The K PDF is shown in Fig. 4 where the PDF right hand tail spreads out more and the peak decreases as the turbulence strength increases. Note that as $\alpha_R \rightarrow \infty$, the K distribution tends towards a negative exponential distribution.



Fig. 4: K PDFs against h for different strong turbulence values.

2.1.4 Negative Exponential Turbulence Model

For a large number of independent scattering and propagation paths spanning several kilometres, the optical signal experiences very strong irradiance fluctuation and the turbulence regime is known as the saturated (i.e. fully developed speckle [19]) regime [7, 21]. Theoretical and experimental verifications have proved that negative exponential statistics are suitable for modelling the saturated turbulence regime [19]. The PDF of the negative exponential is given by [6, 19]

$$f_{NE_{I}}(I,\langle I\rangle) = \frac{1}{\langle I\rangle} \exp\left(-\frac{I}{\langle I\rangle}\right); \qquad I > 0;$$
(15)

Also, the negative exponential PDF is obtained with respect to h as

$$f_{NE_h}(h) = \exp(-h); \qquad I > 0; \tag{16}$$

The negative exponential PDF is shown in Fig. 5. As expected, the PDF is similar to those obtained with the gamma-gamma and K distributions at very strong turbulence regimes.



Fig. 5: Negative exponential PDFs against h for different average irradiance values.

In addition to the turbulence models mentioned above, the weak to strong turbulence regime can be modelled with the I-K and lognormal-Rician distributions. Note that the K, lognormal-Rician, I-K and gamma-gamma turbulence models all tends towards the negative exponential turbulence model in very strong to saturated turbulent regimes [19].

III. ATTENUATION DUE TO BEAM SPREAD AND THE ATMOSPHERIC CHANNEL

Beam spreading is a distance dependent impairment which refers to an increment in the transmitted beam divergence angle as it propagates the atmosphere thereby reducing the amount of radiation captured by the receiver (shown in Fig. 6) [2, 22]. With assumptions that no obstructions exist between the transmitter and the receiver, that the transmitted power has a uniform distribution and that the transmitter diameter is very small, the loss due to beam spread in an FSO link can be given as [22-24]

$$L_{bs} = \left(\frac{d_{rx}}{d_{bD}}\right)^2 \tag{17}$$

where d_{rx} represents the receiver diameter and $d_{bD} = \phi D$ represents the beam diameter due to diffraction alone where ϕ and D represents the beam divergence angle and propagation distance respectively.

The attenuation experienced by the optical signal as it propagates through the atmosphere is dependent on the channel visibility and varies with time. The atmospheric attenuation is given by the Beer-Lambert's law as [2, 25]

$$L_{atm} = \exp(-\alpha D)$$

(18)

where α (a function of scattering and absorption) represents the atmospheric attenuation factor. With the impact of absorption largely negligible, α (assuming the Mie scattering model) is given as [2]

$$\alpha = \frac{3.91}{V} \left(\frac{\lambda}{550nm}\right)^{-\delta} \tag{19}$$

where V, λ and δ represents the atmospheric visibility (the longest horizontal atmospheric distance through which an object is visible), operating wavelength of the laser source and a parameter (values given by the kim [26] and kruse [27] models) related to visibility and distribution of particle size in the propagation path respectively.



Fig. 6: Diagrammatic representation of an FSO link.

IV. ATTENUATION DUE TO POINTING AND COUPLING LOSSES

Pointing loss occurs due to inability to perfectly align the transmitter and receiver. Misalignments can be caused by strong winds and building sway. While alignment issues can be overlooked in links over short distances, they are more significant in long distance transmission where the transmitted signal can be misdirected such that it essentially misses the receiver completely. Pointing loss has a detrimental effect on system performance. However, with increased implementation cost, responsive tracking systems can be used to automatically align the transmitter with the receiver thereby mitigating the effect of pointing error [2, 28-30].

Under the assumptions that the received beam is Gaussian, the receiver aperture is circular and the radial displacement from the beam centre axis r follows a Raleigh distribution model, the probability density distribution of the attenuation due to pointing error and beam spreading is given as [28, 30, 31]

$$f_{h_p}(h_p) = \frac{\varsigma^2}{a_0^{\varsigma^2}} h_p^{\varsigma^2 - 1}; \qquad 0 \le h_p \le a_0$$
(20)

where $\zeta = w_{\xi_{eq}}/2\sigma_s$, σ_s represents the standard deviation of the pointing loss displacement at the receiver, $w_{\xi_{eq}}$ represents the equivalent beam width, a_0 represents the fraction of the power collected by the receiving

lens and h_p represents attenuation due to pointing error and beam spreading.

When fibre components are integrated into FSO links (i.e. systems with optical amplifiers (OAs) and wavelength-division multiplexing (WDM) networks), loss occurs as the optical signal is coupled into the fibre. The coupling loss is largely due to a turbulence-induced reduction in the atmospheric coherence length and while adaptive optics can be used to mitigate its effect, it is customary to include a coupling loss penalty in the link budget [7, 23, 24, 32].



Fig. 7: Flowchart showing a MC simulation technique for modelling system parameters affected by atmospheric turbulence.

V. MODELLING OF SYSTEM PARAMETERS UNDER ATMOSPHERIC TURBULENCE CONDITIONS WITH MONTE CARLO SIMULATION METHODS

MC simulation (also known as statistical sampling) is a computational technique used to obtain numerical results by repetitive random sampling. It is particularly useful in applications where it is either too complicated or impossible to use other mathematical methods [33]. Due to the random effect of atmospheric turbulence which, in some cases, overstretches analytical methods when used, MC simulation methods are used in several aspects of this work. The MC simulation technique (flowchart shown in Fig. 7) involves the generation of random numbers that follows pre-defined turbulence distributions. To generate a sample random

variable of a particular turbulence distribution, a uniform random variable (i.e. U(0,1)) can be used to give a

value for the cumulative distribution function (CDF) of the turbulence distribution, which is mapped to the appropriate argument and thus directly samples the desired input PDF. By performing repetitive sampling, a histogram approximating to the PDF corresponding to the particular turbulence distribution and more particularly, functions of its samples can be obtained for different system parameters. The system parameters are then used to analyse system performance. This approach is particularly computationally convenient and useful in cascaded FSO links.

VI. SCINTILLATION MITIGATION TECHNIQUES

Some of the methods already proposed in literature for scintillation mitigation are summarised below

- Aperture averaging: This technique involves making the receiver aperture size bigger than the correlation length of the intensity fluctuation such that the signal fluctuations are averaged over the receiver aperture size [1, 12]. While aperture averaging has been shown to be effective (even in strong turbulence [34]), it is sometimes expensive or impractical to make the aperture size bigger than the correlation length of the intensity fluctuation [35, 36].
- 2) Spatial diversity: This technique ensures that multiple faded versions of the same signal are collected at the receiving end. In order to prevent correlated fading (and ensure improved system performance [36]), the spatial separation between the transmitting and/or receiving lenses should be made bigger than the coherence length of the intensity fluctuation [37]. Spatial diversity can be realised either as multiple transmitters sending signals to multiple receivers (MIMO), multiple transmitters sending signals to a single receiver (MISO) or a single transmitter sending signals to multiple receivers (SIMO) [9, 15]. The practical realization of a spatially diverse system is costly due to the multiple transmitters/receivers required and difficult to implement because of the transmitter and receiver alignment requirements [36].
- 3) Maximum likelihood sequence detector (MLSD): This technique jointly detects multiple symbols depending on the statistical and temporal characteristics of the channel [38]. MLSD has been analysed for instances where channel state information (CSI) is known and when it's not known [38, 39]. Even though MLSD has been shown to efficiently mitigate scintillation, its complicated operation (i.e. performing multidimensional integration) makes it less attractive [35].
- 4) Forward error correction (FEC) with interleaving: The FEC technique involves the addition of error correcting codes to the transmitted information. If the errors in the received signal are minimal, FEC can easily be used to recover the original transmitted information. However, for burst errors (possible in FSO communication systems due to atmospheric turbulence), FEC becomes less efficient for information recovery. Using interleaving with FEC is beneficial in a turbulent atmosphere. Interleaving involves a reshuffling process (which reduces the effect of burst errors) at the transmitting and receiving ends such that the recovery performance of FEC is improved even when burst errors occur [40, 41].
- 5) Cooperative diversity and multi-hop transmission: This technique involves the introduction of relays nodes in-between the transmitter and receiver. The configuration of the relay nodes could be serial (i.e. multi-hop) or parallel (i.e. cooperative diversity) [42]. The relaying method can be further characterised based on their mode of operation as shown below.
 - I. Amplify-and-forward (AF): At each relay node, the received optical signal is first normalized to unity after which the relay modulates the signal with the transmitter power. The signal is then retransmitted to another relay or the receiver. This method ensures that, at each relay point, the optical signal is transmitted with the same power as the transmitter power [25, 42, 43].
- II. Decode-and-forward (DF): At each relay node, the received optical signal is decoded and directly modulated with the transmitter power. The signal is then retransmitted to another relay or the receiver. This process only takes place if the received signal-to-noise ratio exceeds a pre-determined decoding threshold [42, 44, 45].
- 6) Use of a saturated OA: This technique exploits the saturation characteristics of the OA gain (i.e. the ability of the OA to adapt its gain to new power levels by providing lower gains to higher input powers and higher

gains to lower input powers) with the assumption that the gain dynamics is faster relative to atmospheric turbulence [46-48]. This method will form part of the focus of the present work.

VII. CONCLUSION

This paper reviewed the atmospheric channel through which the transmitted optical signal propagates. Impairments such as obstacles along the propagation path, absorption, scattering and atmospheric turbulence were discussed. Various models used to characterise the turbulent channel were reviewed. The lognormal turbulence model is known to be valid in the weak turbulence regime and the gamma-gamma turbulence model (which covers the weak to strong turbulence regime) gives results that are similar to experimental results. The K and negative exponential turbulence model are suitable for the strong and saturated turbulence regimes respectively. The impact of the attenuation due to beam spreading, atmospheric channel, pointing and coupling losses on the transmitted optical signal were discussed in this paper. The use of MC simulation techniques for modelling atmospheric turbulence was discussed and some turbulence mitigation methods were examined.

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